

# Transfer Learning: Statistical Perspectives

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# Why Transfer Learning? A Realistic Motivating Example

## Scenario: Deploying a model under distribution shift

You trained a predictive model on **City A** (abundant historical data) but must deploy in **City B** (new sensors, limited labels). Examples: traffic speed forecasting, demand prediction, air-quality mapping, health-risk scoring, fraud detection.

## What changes in practice (typical sources of shift)?

- **Population / behavior:** commuting patterns, purchasing habits, patient mix.
- **Measurement system:** sensor placements, missingness patterns, device calibration.
- **Environment & policy:** road network changes, new regulations, seasonality differences, interventions.

**Transfer learning goal.** Use *large source data* to learn reusable structure, then *adapt* using *limited target data* to reduce target error and avoid negative transfer.

# Problem Setup and Guiding Questions

**Setup.** Training data come from a *source* distribution, but deployment occurs on a (possibly different) *target* distribution:

$$(X, Y) \sim P_s \text{ (source)} \implies (X, Y) \sim P_t \text{ (target)}, \quad P_s \neq P_t.$$

**Objective.** Learn a predictor  $f$  that minimizes the *target risk*

$$R_t(f) = \mathbb{E}_{(X, Y) \sim P_t} [\ell(f(X), Y)],$$

potentially leveraging *source* data and limited *target* supervision, while avoiding *negative transfer*.

## Guiding questions.

- 1 **What to transfer?** instances, representations, parameters, priors, or structure
- 2 **When to transfer?** quantify mismatch; select/weight sources; detect negative transfer
- 3 **How to transfer?** reweighting, alignment, adaptation, regularization, meta-learning, fine-tuning

# What Changes from Source to Target? A Shift Taxonomy

Transfer learning is not a single problem: **which part of the data-generating process changes** determines what is feasible.

## Common shift types (with canonical assumptions)

- **Covariate shift:**  $P_s(X) \neq P_t(X)$  but  $P_s(Y | X) = P_t(Y | X)$ .
- **Label shift:**  $P_s(Y) \neq P_t(Y)$  but  $P_s(X | Y) = P_t(X | Y)$ .
- **Conditional / concept shift:**  $P_s(Y | X) \neq P_t(Y | X)$  (hardest; requires structure).

**Target risk.** Under covariate shift,

$$R_t(f) = \mathbb{E}_{(X,Y) \sim P_s} \left[ \underbrace{\frac{P_t(X)}{P_s(X)}}_{w(X)} \ell(f(X), Y) \right],$$

which motivates *importance weighting* if  $w(X)$  can be estimated and overlap holds.

# Statistical Takeaway: What Must Be Answered Under Shift?

## The key questions become:

- 1 **Identifiability:** What target quantities are *estimable* from available source/target data under the assumed shift?
- 2 **Robustness:** What happens if the assumed shift is *slightly wrong*? Can we control worst-case or sensitivity?
- 3 **Uncertainty:** How confident are we on the target (e.g., valid CIs / prediction intervals / calibrated uncertainty)?

**Practical implication.** A “good” transfer method should (i) state its shift assumptions clearly, (ii) degrade gracefully when assumptions fail, and (iii) quantify when transfer may be harmful (negative transfer).

# Where Is Statistical Transfer Learning Focused Today?

## Current focal points

- **Transportability / generalizability:** conditions under which target risk/effects are identifiable from biased or shifted data.
- **Shift-aware estimation:** importance weighting, doubly-robust estimators, and semiparametric efficiency under covariate/label shift.
- **Uncertainty quantification:** valid inference on the target (CIs, prediction intervals, calibration) under shift and limited target labels.
- **Robustness & safety:** distributionally robust objectives (e.g.,  $f$ -divergence / Wasserstein balls) and negative-transfer control.
- **Multi-source borrowing:** source selection/weighting, hierarchical (empirical Bayes) shrinkage, and adaptive regularization.
- **Structured domains:** transfer on graphs, time series, and spatial data via interpretable inductive biases (smoothness, low-rank, graphon).

# Deep Transfer Learning: Current Focus

**Main idea:** learn *general representations* from large data, then *adapt quickly* to new tasks/domains.

## What the field is optimizing for

- **Pretraining** → **transfer:** self-supervised / foundation models + fine-tuning or prompting.
- **Cheap adaptation:** parameter-efficient tuning (adapters/LoRA) instead of full retraining.
- **Little/no target labels:** domain adaptation via alignment + pseudo-labeling/self-training.
- **Robustness to new domains:** OOD generalization and test-time adaptation.
- **Long-term deployment:** continual learning (avoid forgetting as domains shift over time).

**Summary.** *Scale representations, adapt efficiently, stay stable under shift.*

**Main idea:** transfer under *explicit shift assumptions*, with *validity* and *uncertainty* on the target.

What the field is optimizing for

- **Shift assumptions:** what changes from  $P_s$  to  $P_t$ ?
- **Safe borrowing:** weighting, shrinkage/priors, multi-source selection.
- **Robustness:** avoid negative transfer under mismatch.
- **Uncertainty:** calibrated prediction and valid intervals on target.

**Summary.** *Make assumptions explicit, borrow cautiously, quantify uncertainty.*

# When Does Negative Transfer Happen?

**Negative transfer:** using source information makes target worse:

$$R_t(f_{\text{transfer}}) > R_t(f_{\text{target-only}}).$$

- **Mismatch is large:** weak overlap / different regimes between source and target.
- **Wrong invariance:** assuming  $P_s(Y|X) = P_t(Y|X)$  when it actually changes.
- **Shortcut features:** model transfers spurious correlations that do not hold in target.
- **Too much source pull:** strong priors/alignment blocks target-specific fitting.
- **Self-training errors:** noisy pseudo-labels reinforce mistakes (confirmation bias).

**Practice:** estimate mismatch, down-weight unreliable sources, and keep a target-only baseline.

# My Research (I): Phase Transition in Transfer Learning

**Focus.** When is transfer *beneficial* versus *harmful* under distribution shift?

## Key contribution

- **Phase transition:** characterize a threshold (in target sample size and/or source–target mismatch) where the optimal strategy switches from *borrowing source information* to *target-only fitting*.
- **Mechanism:** formalize the bias–variance tradeoff induced by source regularization/priors, and identify regimes that lead to **negative transfer**.

**Method.** Adaptive transfer strength (data-driven shrinkage):

transfer weight  $\uparrow$  when similarity/overlap is high,  
transfer weight  $\downarrow$  when mismatch is high.

# My Research (II): Graphon-Based Transfer for Networks

**Focus.** Transfer learning for *network structure*: estimate target edge probabilities with limited/noisy target graphs.

## Key contribution

- **Graphon model:** represent each network by a latent edge-probability function, capturing shared structure across domains.
- **Transfer via alignment:** match latent positions/blocks between source and target (e.g., OT-based matching), then borrow information to improve target estimation.

**Methodological shift.** From black-box transfer to **model-based transfer**:

latent structure learning & alignment  $\Rightarrow$  transport of edge-probability information  
 $\Rightarrow$  improved target estimation.

# My Research (III): SCOT — Cross-City Transfer via Optimal Transport

**Focus.** Cross-city transfer for urban prediction (e.g., mobility / socio-economic signals) when target labels are scarce.

## Key contribution

- **OT alignment of regions:** learn city-specific region embeddings and compute a Sinkhorn OT coupling to match regions across cities.
- **OT-guided transfer:** use the coupling to (i) align representations and (ii) weight contrastive objectives, improving cross-city generalization.
- **Structure preservation:** incorporate reconstruction/geometry terms so the alignment respects local neighborhood semantics.

**Method.** A principled pipeline for cross-city transfer:

- learn region embeddings  $\Rightarrow$  Sinkhorn OT coupling (region matching)
- $\Rightarrow$  OT-guided alignment + reconstruction
- $\Rightarrow$  improved target prediction.

# Transfer Learning Strategies (I): What to Transfer?

## Four common transfer “objects”

- **Instance:** reuse (reweighted) source samples,  $w(x) \approx \frac{p_t(x)}{p_s(x)}$ .
- **Representation:** learn features  $h(\cdot)$  that reduce source–target mismatch (alignment).
- **Parameter:** reuse/shrink parameters or priors, e.g.  $\|\theta - \hat{\theta}_s\|^2$ .
- **Structure:** transfer relational patterns (graph/space/time dynamics).

**Rule of thumb:** pick the transfer object that is most likely *invariant* across domains.

# Transfer Learning Strategies (II): Which Setting Are You In?

**Setting = domain/task relationship + target label availability.**

## Canonical settings

- **Inductive transfer learning: tasks differ** ( $\mathcal{T}_s \neq \mathcal{T}_t$ ), target has (some) labels.  
Typical: pretrain  $\rightarrow$  fine-tune; multitask learning; meta-learning.
- **Transductive transfer learning (domain adaptation): same task, different domains** ( $\mathcal{D}_s \neq \mathcal{D}_t$ ), target labels scarce/none.  
Typical: feature alignment (MMD/adversarial/OT) + self-training/pseudo-labels.
- **Unsupervised transfer learning:** target task is unsupervised (e.g., clustering/representation); labels absent in target (often both).  
Typical: transferable embeddings, self-supervised objectives.

# How to Think About Transfer Learning (A Checklist)

## A practical way to formulate a TL problem

- 1 **Specify the shift:** what differs between source and target (data, labels, mechanism, structure)?
- 2 **Specify supervision:** how many target labels, and what is available at test time?
- 3 **Choose the transfer object:** instance / representation / parameter / structure.
- 4 **Pick the control knob:** how strongly to trust the source (e.g.,  $\lambda$  in a transfer penalty).
- 5 **Define success & safety:** target risk + robustness (avoid negative transfer; add uncertainty/calibration if needed).

**Template:**  $\min_f \widehat{R}_t(f) + \lambda \Omega(f; \text{source, target})$  (fit target) + (transfer / alignment / prior)

# Where Are the Innovation Opportunities in Transfer Learning?

Most TL papers contribute by changing one (or more) of these pieces

- **Better shift modeling:** new assumptions, new invariances, causal/structural views of what transfers.
- **Better transfer mechanism  $\Omega$ :** e.g., OT-based matching, graph/time-aware alignment.
- **Better source selection/weighting:** decide *which* sources to trust and *how much* (adaptive  $\lambda$ ).
- **Better training protocol:** pretrain  $\rightarrow$  adapt; meta-learning; test-time adaptation; continual adaptation.
- **Better safety tools:** negative-transfer detection, robustness objectives (DRO), calibrated uncertainty / conformal prediction.
- **Better evaluation:** realistic shifts, multi-source benchmarks, ablations for “what transfers” and “when it fails”.